

Multi-dof continued

$$\text{recall: springs + masses: } M \ddot{\vec{x}} + K \vec{x}' = \vec{0} \quad (1)$$

$$\text{initial conditions: } \vec{x}'(0) = \vec{v}_0, \vec{x}(0) = \vec{x}_0 \quad (2)$$

$\underbrace{\hspace{10em}}_{\text{constants}}$

How to solve (1) and (2): Initial Value Problem

Algorithm

1. guess: $\vec{x}' = \vec{x} e^{i\omega t}$ $\vec{x} = \text{constant}$

plug into (1) from above

2. equation reads: $\underbrace{(-\omega^2 M + K)}_A \vec{x} = \vec{0}$

$$\det(A) = 0 \rightarrow \text{polynomial in } \omega^2$$

Example: 2x2 matrix \rightarrow quadratic equation in ω^2

$$\omega_1 = +\sqrt{\omega_1^2}$$
$$\omega_2 = +\sqrt{\omega_2^2}$$

\rightarrow positive real roots because M, K are positive matrices

(3) For ω_1 , we solve $(-\omega_1^2 M + K) \vec{x} = 0$

get \vec{x}_1

For ω_2 , we solve $(-\omega_2^2 M + K) \vec{x} = 0$

get \vec{x}_2

etc. (for higher order matrices)

(4) General Solution:

$$\vec{x}(t) = c_1 \vec{x}_1 e^{i\omega_1 t} + c_2 \vec{x}_2 e^{i\omega_2 t} + \dots \leftarrow \text{for more } \vec{x}'\text{'s}$$

Real Solution

$$= \vec{x}_1 [c_{1c} \cos \omega_1 t + c_{1s} \sin \omega_1 t] + \vec{x}_2 [c_{2c} \cos \omega_2 t + c_{2s} \sin \omega_2 t]$$

⑤ Initial Value Problem

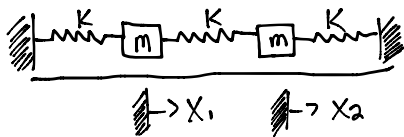
④ Implies $\vec{x}(0), \vec{x}'(0)$

$$\text{set } \vec{x}(0) = \vec{x}_0, \vec{v}(0) = \vec{v}_0$$

4 equations for $C_{1s}, C_{1c}, C_{2s}, C_{2c}$

-put in 8 numbers and got out 12

Example:



$$\text{LMB: } m_1: m_1 \ddot{x}_1 + K_1 x_1 - K(x_2 - x_1) = 0$$

$$m_2: m_2 \ddot{x}_2 + K x_2 + K(x_2 - x_1) = 0$$

$$\underbrace{\begin{bmatrix} m_1 & 0 \\ 0 & m_2 \end{bmatrix}}_M \ddot{\vec{x}} + \underbrace{\begin{bmatrix} 2K & -K \\ -K & 2K \end{bmatrix}}_K \vec{x} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

1.) guess $\vec{x} = \vec{x} e^{i\omega t} \rightarrow \det(-\omega^2 M + K) = 0$

$$\det \begin{bmatrix} 2K - \omega^2 m & -K \\ -K & 2K - \omega^2 m \end{bmatrix} = 0$$

$$(2K - \omega^2 m)^2 - K^2 = 0$$

$$4K^2 - 4K\omega^2 m + (\omega^2)^2 m^2 - K^2 = 0 \quad \omega^2 \rightarrow \text{variable}$$

$$m^2 (\omega^2)^2 - 4K m \omega^2 + 3K^2 = 0$$

$$\omega^2 = \frac{4K m \pm \sqrt{16K^2 m^2 - 12K^2 m^2}}{2m^2} = \frac{K}{M} (\alpha \pm \sqrt{4-3})$$

$$\omega_1 = \sqrt{\frac{3K}{m}}, \omega_2 = \sqrt{\frac{K}{m}}$$

Solve equation ③ plug in one of the roots

$$\omega_1^2 = \frac{K}{m} \quad \begin{bmatrix} K & -K \\ -K & K \end{bmatrix} \begin{bmatrix} \bar{x}_1 \\ \bar{x}_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\bar{x}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\omega_2^2 \rightarrow \bar{x}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

general solution :

$$\vec{x}(t) = \begin{bmatrix} 1 \\ 1 \end{bmatrix} (C_{1c} \cos \sqrt{\frac{K}{m}} t + C_{1s} \sin \sqrt{\frac{K}{m}} t) + \begin{bmatrix} 1 \\ -1 \end{bmatrix} (C_{2c} \cos \sqrt{\frac{3K}{m}} t + C_{2s} \sin \sqrt{\frac{3K}{m}} t)$$